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Methods for the calibration of vibration and shock transducers —

Part 17: Primary calibration by centrifuge

Méthodes pour l'étalonnage des transducteurs de vibrations et de chocs —

Partie 17: Étalonnage primaire par centrifugeur

Reference number
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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

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For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html.

The committee responsible for this document is ISO/TC 108, *Mechanical vibration, shock and condition monitoring*, Subcommittee SC 3, *Use and calibration of vibration and shock measuring instruments*.

This first edition of ISO 16063-17 cancels and replaces ISO 5347-7:1993, which has been technically revised.

ISO 16063 consists of the following parts, under the general title *Methods for the calibration of vibration and shock transducers*:

— *Part 1: Basic concepts*

— *Part 11: Primary vibration calibration by laser interferometry*

— *Part 12: Primary vibration calibration by the reciprocity method*

— *Part 13: Primary shock calibration using laser interferometry*

— *Part 15: Primary angular vibration calibration by laser interferometry*

— *Part 16: Calibration by Earth's gravitation*

— *Part 17: Primary calibration by centrifuge*

— *Part 21: Vibration calibration by comparison to a reference transducer*

— *Part 22: Shock calibration by comparison to a reference transducer*

— *Part 31: Testing of transverse vibration sensitivity*

— *Part 32: Resonance testing — Testing the frequency and the phase response of accelerometers by means of shock excitation*

— *Part 41: Calibration of laser vibrometers*

— *Part 42: Calibration of seismometers with high accuracy using acceleration of gravity*

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— *Part 43: Calibration of accelerometers by model-based parameter identification*

The following parts are under preparation:

— *Part 33: Testing of magnetic field sensitivity*

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Methods for the calibration of vibration and shock transducers —

Part 17: Primary calibration by centrifuge

1 Scope

ISO 16063 comprises a series of documents dealing with methods for the calibration of vibration and shock transducers.

This part of ISO 16063 lays down detailed specifications for the instrumentation and procedure to be used for primary calibration of accelerometers using centrifuge calibration.

This part of ISO 16063 is applicable to rectilinear accelerometers with zero-frequency response, mainly of the strain gauge or piezoresistive type, and to primary standard and working transducers.

It is applicable for a calibration range from 10 m/s^2 to 20 000 m/s^2 (higher accelerations possible) at 0 Hz.

The limits of uncertainty applicable are ±1 % of reading.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 2041, *Mechanical vibration, shock and condition monitoring — Vocabulary*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 2041 apply.

4 Requirements for apparatus and environmental conditions

4.1 Calibration environment

The standard reference atmospheric conditions are: (23 ± 3) °C and 75 % relative humidity max. The temperature, humidity and atmospheric pressure shall be measured and reported.

4.2 Balanced table or arm (rotational table)

The main component of the calibration apparatus consists of balanced table or arm which rotates about a vertical axis with uniform angular speed. For the calibration range from 10 m/s^2 to 100 m/s^2, the table/arm shall be level within ±0,5° of horizontal. For ranges higher than 100 m/s^2, levelling is allowed to within ±2°. The calibration apparatus shall be placed on a sufficiently heavy base which is sufficiently isolated from the floor vibration.

The rotational frequency shall be uniform within ±0,05 % of the nominal value.

The transducers axis of sensitivity shall be aligned within ±0,5°.

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